

# CS 341 - W24

## Algorithms

## Full Course Notes

With Prof Armin Jamshidpey

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I took in-class notes and mostly avoided writing examples. I hope this high-level summary helps!

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[Josiah Plett](#)

# CS 341 Notes 1

## 1 Intro Lecture

★ Second half of the course is harder

★ Every single question comes with proof of correctness & runtime.

## Syllabus

- divide&conquer, master theorem
- breadth-first, depth-first
- greedy algorithms
- dynamic programming
- NP-completeness

$T(I)$  = runtime on input  $I$

$T(n) = \max_{I \text{ of size } n} T(I)$

★ Great idea to memorize formulae for  $\underline{O(n)}$ ,  $\underline{\Omega(n)}$ ,  $\underline{o(n)}$ ,  $\underline{\omega(n)}$ ,  $\underline{\Theta(n)}$

## 3 Divide-and-Conquer

### Substitution Method

To solve a recurrence relation:

1. Guess the solution (or its form)
2. Use induction to prove it.

### Divide-and-Conquer

Divide: split problem into mutually exclusive subprobs.

Conquer: Solve subproblems (recursively) w/ same alg.

Combine: Use subproblem result to derive final result.

## 2 Solving Recurrences

In this class, we use the artificial computation model; ignore memory, data locality etc.  
(Also, index 0  $\rightarrow$  index 1!)

### Multiple Parameters

$f(n, m) \in O(g(n, m))$  if  $\exists C, m_0, n_0$   
s.t.  $f(n, m) \leq Cg(n, m)$  for  
 $n \geq n_0$  and/or  $m \geq m_0$

### Computational Model: word RAM

- word size  $\geq \log(n)$  for any  $n$
- operations + accesses are unit cost

This is inexact; if we want a formal proof for non-power values of  $N$ , then we can use the MASTER THEOREM.

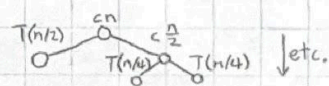
### Recurrence

$$T(n) = \begin{cases} T(n/2) \times 2 + \Theta(n) & \text{if } n > 1 \\ \Theta(1) & \text{if } n = 1 \end{cases}$$

### Sloppy Recurrence

$$T(n) = \begin{cases} 2T(n/2) + cn & \text{if } n > 1 \\ d & \text{if } n = 1 \end{cases}$$

### Recursion Tree



### Runtime

$$cn + cn + \dots + cn + d \cdot n = \Theta(n \log n)$$

### Master Theorem

Suppose  $a \geq 1$  and  $b > 1$  from

$$T(n) = aT\left(\frac{n}{b}\right) + \Theta(n^d)$$

Denote  $x = \log_b a$  Then:

$$T(n) \in \begin{cases} \Theta(n^x) & \text{if } y < x \\ \Theta(n^d \log n) & \text{if } y = x \\ \Theta(n^d) & \text{if } y > x \end{cases}$$

• Inversion:  $(i, j)$  where  $i < j$  and  $A[i] > A[j]$

## Solving Problems

- 1 Understand the problem Definition.
- 2 Come up with "a solution" (eg. brute force) and expect to fail.
- 3 Improve your approach until you have GREATNESS!

## Important Tools

- Define mutually exclusive cases
- "Recursive" approach
- Dynamic: divide into subproblems

## 4 Algorithms We Should Know

### Karatsuba's (polynomial multiplication)

$\in \Theta(n^{\log_2(3)})$  by combining  $F_0G_1 + F_1G_0$  into  $(F_0 + F_1)(G_0 + G_1) - F_0G_0 - F_1G_1$

### Toom-Cook

(better Karatsuba's)

$$\in \Theta(n^{\log_k(2k+1)})$$

### Strassen's (matrix multiplication)

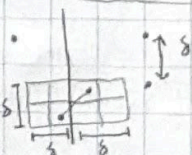
$$\in \Theta(n^{\log_2(7)}) \text{ via 7 multiplications!}$$

### Linear Quick Select (median of medians)

1. Median of medians (2/3 groups of 5)
2. Median select recursively!  $T(n) \in O(n)$

### Closest Pairs

1. Split in half
2. Recurse
3. Solve transverse pairs:
  - a. Boxes! compare to next 7 points



$$\Theta(n \log n)$$

## 5) Breadth First Search

### Undirected Graph ★

Def:  $G=(V, E)$  with  $|V|=n, |E|=m$

Data Structures:

- Adjacency list:  $A[1..n]$  s.t.  $A[v]$  is a linked list of  $v$ -connected edges.  
Size:  $\Theta(n+m)$  Edge exists:  $O(1)$
- Adjacency matrix: binary matrix of size  $n \times n$  w/  $M[v,w]=1$  iff  $\{v,w\} \in E$ .  
Size:  $\Theta(n^2)$  Edge exists:  $O(1)$

You should know these from Math239:

path:  $v_1, \dots, v_k$  s.t.  $\forall \{v_i, v_{i+1}\} \in E$

connected graph:  $\forall v, w \in V, \exists$  path  $v \rightsquigarrow w$

cycle: path  $v_1, \dots, v_k, v_1$  with  $k \geq 3$  and <sup>no repeat vertices</sup>

tree: connected graph with no cycles.

rooted tree: tree with special vertex "root"

Subgraph: strictly inside  $G$  & you know

connected component: maximal connected subgraph of  $G$ .

### BFS Tree ★

$O(n+m)$

Definition: subgraph made of:

- all  $w$  s.t.  $\text{parent}[w] \neq \text{NIL}$
- all  $\{w, \text{parent}[w]\}$ , for  $w$  as above (except  $w=s$ )

## 10) Greedy Algorithms

### Hamiltonian Paths ★

Simple path that visits every vertex exactly once.

for undirected  $G$ : np-complete

for directed  $G$ :  $O(n+m)$

### Greedy Paradigm

"Don't think ahead"

EXAMPLES

- Interval Scheduling
- Interval colouring
- Minimizing completion time
- Dijkstra's algorithm
- Min spanning trees.

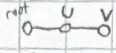
## 6,7) Depth First Search

### DFS Algorithm ★

idea: as deep as possible, then backtrack  
structure: use a stack (recursion/queue)

shortest paths? no

runtime:  $O(n+m)$

ancestor/descendant:   
 $u$  is ancestor of  $v$ ;  $v$  is descendant of  $u$

Back edge: edge in  $G$  that's not a tree edge in our DFS tree.

Cut vertex: vertex  $v$  in connected  $G$  s.t.  $G \setminus v$  is disconnected.

### Cut Vertex Claim ★

For any  $v \neq s$ ,  $v$  is a cut vertex iff it has a child  $w$  with  $m(w) \geq \text{level}[v]$  ( $m \rightarrow$  smallest descendant neighbour)

↳ see bottom of this page.

★ A Directed Graph is a DAG of disjoint strongly connected components.

### Kosaraju's Alg ★

For a directed graph  $G$ , the transpose graph  $G^T=(V, E^T)$  is the graph with edges reversed.

Compute strongly connected components:

$\text{SCC}(G)$ :

- 1 run DFS on  $G$ , record finish times.
- 2 run DFS on  $G^T$ , with vertices ordered in decreasing finish time.
- 3 return trees in DFS forest of  $G^T$ .

### Exchange Argument ★

Essentially: prove any swap between elements cannot create a more optimal solution

$\alpha(v) = \min(\text{level}[w])$ , where  $\exists \{v, w\} \in E$   
 $m(v) = \min(\alpha(w))$ , where  $w$  descendant of  $v$

## 8) Directed Graphs

DAG: directed acyclic graph.

## 9) Connectedness

### Testing Acyclicity

$G$  has a cycle IFF there is a back edge in its DFS forest.

### Topological Ordering

Suppose  $G=(V, E)$  is a DAG.

A topological order is an ordering  $(\prec)$  of  $V$  s.t.

$\forall e=(v, w) \in E$ , we have  $v \prec w$ .

### Strong Connectivity

iff  $\forall v, w \in G, v \rightsquigarrow w$

Testing Strong Connectivity

Explore twice from  $s \in V$ , once with edges reversed.

### Strongly Connected Component

- Subgraph of  $G$
- which is strongly connected
- not contained in another strongly connected subgraph



## 11) Greedy Algorithm Correctness

### Greedy Alg Stays Ahead

- 1 Define an optimal outcome and a greedy outcome.
- 2 Prove the greedy outcome always returns an equal or better result than optimal.  
↳ induction ↳ contradiction

## 12 Minimum Spanning Trees

Min Spanning Tree: spanning tree with minimal weight.

### Kruskal's Alg

Greedy alg for minimum spanning T:

- Take smallest edge
- If made cycle, undo!

$$O(m \log(m) + n^2)$$

### Exchanging Edges

Let  $(V, A)$  &  $(V, T)$  be spanning trees.  
Let  $e \in T, e \notin A$ .

Then,  $\exists e' \in A, e' \notin T$ , such that  
 $(V, T) + e' - e$  is still a spanning tree.  
Also,  $e$  and  $e'$  are on same cycle.

### Merging Connected Sets

To find if we made a cycle! Use a list of linked lists implementing "give each node a colour representing its group."

## 16 DP Part 4: Bellman-Ford

### Bellman-Ford 2.0

runtime:  $O(mn)$   
Slowly "relaxes" all edges at once, until every vertex has its minimum cost from the root

Solves which Problem?

Dijkstra but negative edges

- $O(m)$  to check for a reachable negative cycle at the end
- Implementable via walking every edge once (in any order),  $n$  times.

## Independent Sets

Independent set  $S$  of  $G=(V, E)$  is  $S \subseteq V$  s.t. there are no edges between nodes of  $S$ .

★ Exercise for Finals practice!

### Floyd-Warshall Algorithm

Compute shortest path between every pair of nodes in a weighted graph (which may have negative weights).

Algorithm:  $\forall k \in V$ , update all  $D[i][j]$  with  $i \rightarrow k \rightarrow j$

$$D = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

where  $D[i][j]$  is shortest known path from  $i \rightarrow j$ , initialized to the weight of a direct edge (if exists)

## 18 Polynomial Time Reduction

Decision Problem: Given instance  $I$ , answer "yes" or "no".  
Size( $I$ ) = # of bits required to specify instance  $I$ .

### Polynomial Time Reduction

$A$  is polynomial time reducible to a decision problem  $B$  if there exists an algorithm  $F$  that transforms all  $I_A$  into an instance  $I_B$  such that

$$I_A \text{ is YES} \Leftrightarrow F(I_A) = I_B \text{ is YES}$$

(we write  $A \leq_p B$  if such a polynomial time reduction exists)

## 20-21 NP-Completeness

### Proving NP

- Understand your input  $S$  & certificate  $t$
- Provide polynomial-time alg for:  $Alg(S, t) \rightarrow \text{YES/NO}$
- Remember, this is only verification

Definition

Co-NP: set of problems whose no-instances are NP.

P: set of problems solvable in polynomial time.

NP-Complete: hardest problem in NP.

### Principle behind NP-C

If  $X$  is NP (verified), then it's the hardest problem in NP iff

$$Y \leq_p X \text{ for all } Y \in \text{NP}$$

## 13 Dynamic Programming

Tool: Dynamic Programming

- Break problem down into subproblems
- Store subproblem solutions  
↳ because they'll overlap; avoid recomputing!

## 14 More Dynamic Programming

(LEC 12 SLIDES)

DP on various substring optimization subproblems.

## 15 Dynamic Programming Part 3

### Longest Common Subsequence

$i \backslash j$	0	1	2	3	4
0	0	0	0	0	0
1	0	1	1	1	1
2	0	1	1	2	2
3	0	1	1	2	2

$M[i, j] = \text{MAX OF:}$

↳  $M[i, j-1]$

↳  $M[i-1, j]$

↳  $\text{IF } A[i] = B[j], 1 + M[i-1, j-1]$

### Spellchecker

3 issues: add, delete, change.

Input: 2 arrays of chars,  $A$  and  $B$

Output: Min # of modifications to turn  $A$  into  $B$ .

## 17 DP Part 5: Floyd-Warshall

## 20-22 NP-Completeness

### NP-Complete Problem Bank

- 3 SAT, SAT  $((x \vee y \vee z) \wedge (\bar{x} \vee y \vee z))$
- Independent set [of size  $k$ ]
- Vertex Cover, Clique [of size  $k$ ]
- Hamiltonian Cycle & Path (directed)
- Travelling Salesman
- Subset sum  $(\sum a_i = k \text{ from array})$
- Binary Knapsack (item:  $\frac{\text{weight}}{\text{value}}$ )

## Proving NP-Completeness

Given: Decision problem  $X$

- ① Prove  $X$  is NP  
↳ Give polynomial-time verification.
- ② Choose  $Q$  from NPC
- ③ Show  $Q$  reduces to  $X$  ( $Q \leq_p X$ )  
↳ Given  $I_Q$ , generate  $I_X$ . (polynomial time)  
↳ Prove that if  $I_Q$  is a yes-instance, so is  $I_X$ , and same for no-instances.  
(or, YES iff YES, or NO iff NO).

## 23-24 NPC Examples

### Perfect 3D Matchings

Input: 3 disjoint sets  $X, Y, Z$  of size  $n$  and a family of hyper-edges  $E \subseteq X \times Y \times Z$   
Decision: is there a perfect matching, which is a full, disjoint-nodes cover?  
Proof idea: make fidget spinners? My takeaway is: construct mini-tools that translate a subproblem of the chosen NPC problem into a subproblem of what you're trying to prove

## NP-Completeness Examples

### Circuit-SAT

Input: DAG with labelled vertices.

Decision: choice of booleans  $x_i$  that make  $v$  true.



Proof: Look, every problem in the world can be built using a DAG with labelled vertices! Since every problem (ever) reduces to it, it's NP-Complete.

### Directed Hamiltonian Cycle

What to reduce to: 3-SAT

Proof idea:

- row of nodes for each variable
- directed edges: left=T, right=F
- node for each clause; connect it smartly

### NOTE

We are not required to understand these proofs for the final! (I only include them for inspiration)



↑ us at the front of class holding numbers for armin's demonstrations ↑